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Advances in hyperspectral remote sensing I: The visible Fourier transform hyperspectral imager

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We discuss early hyperspectral research and development activities during the 1990s that led to the deployment of aircraft and satellite payloads whose heritage was based on the use of visible, spatially modulated, imaging Fourier transform spectrometers, beginning with early experiments at the Florida Institute of Technology, through successful launch and deployment of the Visible Fourier Transform Hyperspectral Imager on MightySat II.1 on 19 July 2000. In addition to a brief chronological overview, we also discuss several of the most interesting optical engineering challenges that were addressed over this timeframe, present some as-yet un-exploited features of field-widened (slit-less) SMIFTS instruments, and present some images from ground-based, aircraft-based and satellite-based instruments that helped provide the impetus for the proliferation and development of entire new families of instruments and countless new applications for hyperspectral imaging.

Keywords: hyperspectral, visible Fourier transform imager, precision agriculture, transportation infrastructure

Introduction

The past ~50 years has seen what can now in hindsight best be described as the debut of a new metadiscipline—hyperspectral remote sensing. Taxonomy previously confined for use by a small and restricted number of specialists has now penetrated virtually every scientific and engineering discipline from agriculture through zoology, although routine use of what has become a very mature technology is not yet ubiquitous across all fields.

Figure 1 depicts the growth of the field, as measured by one readily available metric—how many papers have the word hyperspectral as indexed by Google Scholar. The timeframe can be divided into three main intervals: pre-1990 when use of “hyperspectral” was constant and extremely sparse; the decade of the 1990s when a period of exponential growth occurred; and the post-2000 period with a high linear trajectory to over 10,000 occurrences per year. This paper focusses on just one of many specific technologies (Visible, Fourier

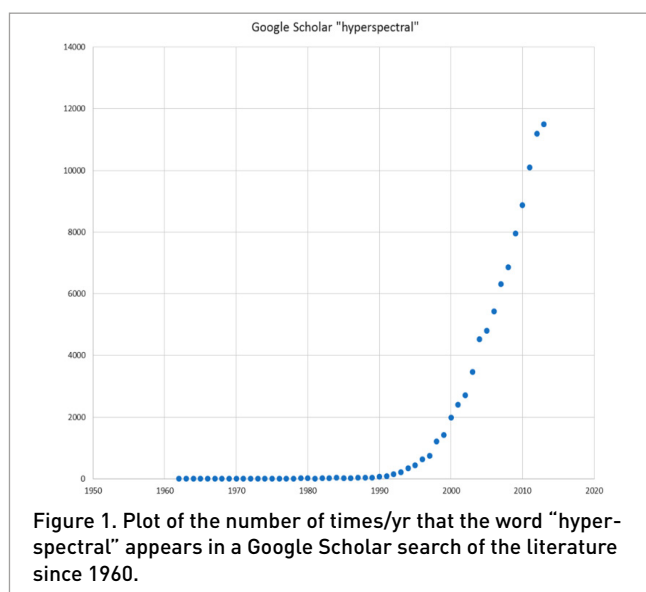


Figure 1. Plot of the number of times/yr that the word “hyperspectral” appears in a Google Scholar search of the literature since 1960.

transform Hyperspectral Imaging—VFTHSI) that contributed to the early growth of the field during the decade of the 1990s, when numerous investigators and laboratories were experimenting and developing a wide array of hyperspectral instrument configurations [e.g., dispersive, Fourier Transform, acousto-optical] in a number of band passes (visible, SWIR, LWIR) for an array of applications. In this paper we will trace the development of just the VFTHSI instrument design heritage—a subset of Spatially Modulated Imaging Fourier Transform Spectrometers (SMIFTS) which also saw the development and impacts of some notable LWIR instruments (Lucey, 1992),¹ from initial brass board implementation to orbit. Topics will include a short review of operational features as seen from the perspective of an optical systems engineer, tracking of the design heritage from brass board to orbit, some observational data from several of the instrument variations and a short summary of unexplored vistas for the future.

VFTHSI basic operational characteristics

Figure 2 depicts the now well-known configuration of a VFTHSI instrument. Shown is a single, polychromatic ray from a target spatial element (x,y) . The ray passes through a fore optic (not shown) with focal length and f /ratio such that infinity focus is at the field stop, which serves only as a spatial mask in the x -direction (but allows image formation in the y -direction). We note that the spatial mask serves primarily to aid in image reconstruction following data reduction, although the wider the spatial mask, the more photons that are admitted to the system—the limiting case being elimination of the field stop entirely. The ray passes through some type of a beam splitter, and hence through the triangle-path or Sagnac interferometer. We also make note that deviations from $R=T=0.5$ split of the ray by the beam splitter across the entire band pass result in rapid deterioration of fringe visibility on the detector, particularly when the instrument is configured for operation near the Nyquist sampling limit. The Sagnac has a number of desirable features including extreme ease of configuration and align-

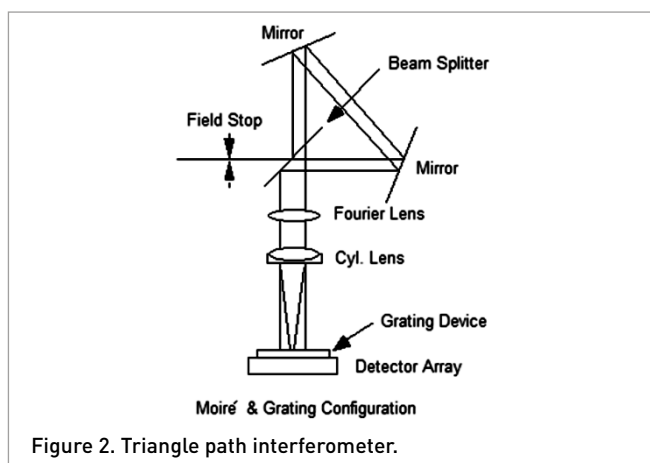


Figure 2. Triangle path interferometer.

ment, and is amenable to monolithic solutions to avoid vibration or misalignment issues. The lower-right mirror in Figure 2 is shown with an offset s from the triangle orientation which introduces a shear in the two mutually coherent parallel rays shown exiting the interferometer downward.

Those two rays enter a Fourier optic, whose focal length is selected to be the distance back through the interferometer to the field stop. Arbitrary magnification [e.g., size of the aperture function necessary to fully illuminate a CCD of size $n \times m$] can be achieved via selection of f /ratio with the fore optic. A cylinder lens whose focal length is chosen to reimage the target y -dimension onto the visible CCD has no power in the (target) x -dimension. The net effect of this optical device for a ray of wavenumber k is that an interferogram, $I(x) = \int I_0(k)/2 \times [1 + \cos(2\pi ks)] dk$, is created on the CCD detector in the (target) x -direction, while the target y -direction creates a one-dimensional image orthogonal to the interferogram on the CCD. A transmission grating (not discussed in this paper) can be placed above the detector, or at other locations in the interferometer, to achieve shifts of the recovered spectrum from the interferogram that more fully cover spatial frequency space.

Tracking the design heritage from brass board to orbit

Our original experiments with the VFTHSI were undertaken on a surplus 2×3 foot brass board at the Florida Institute of Technology—using available surplus beam splitters and surplus optical table components—essentially, nothing more sophisticated than the optics shown in Figure 2. An early version of the brass board was mounted aboard the R1 and R2 telescopes at the Malabar Test Facility, where proof of concept hypercubes were obtained for space objects (space station MIR) as well as cooperative ground-based targets on the Malabar optical range (readily available eight-bit video cameras and image intensifiers were used as the CCD sensors for these early experiments). Concurrently, a utility study was undertaken as part of a larger project funded through Darpa with collaborators from the University of Hawaii and the University of Central Florida.¹ Interestingly, the final report which alluded to “dozens or hundreds” of potential applications for hyperspectral imaging was received with some scepticism, perhaps feeling that such proliferation of applications of such an seemingly limited technology would never occur.

Early success with such modest hardware and demonstration of utility quickly led the US Air Force to provide strong development support for more sophisticated instruments. Figure 3 shows the 3D optical schematic of the Kestrel/Michigan Technological University (MTU) VFTHSI.^{2,3}

The design heritage of the original prototype is retained, although the need to reduce chromatic correction across the band pass led to a number of refinements in the design. The beam splitter is no longer square, becoming more compact

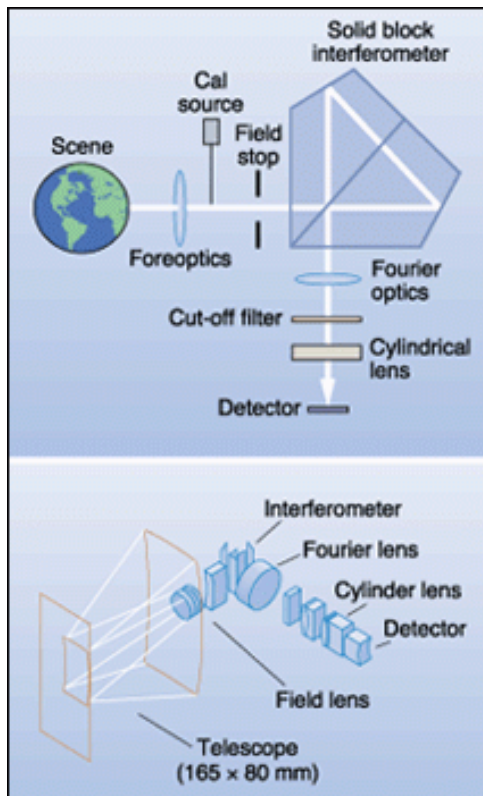


Figure 6. Schematic of the version of VFTHSI that flew in space on MightySat II.1. © 2001 PennWell Corporation. Reproduced from Reference 5 with permission.

vibration and alignment issues during launch and on-orbit operations).

Summary and emerging vistas

As seen from the perspective of 2015, there is now little doubt that hyperspectral remote sensing is in the process of becoming a major remote sensing tool which is being utilised by researchers and practitioners in virtually every scientific and engineering discipline. Recent papers show a broad array of applications where hyperspectral is being applied to predicting beef eating quality,⁶ adulteration levels of lamb,⁷ detection of foreign materials in powdered foods,⁸ mineral exploration,⁹ estimation of lead concentrations in flooded soils,¹⁰ detection of trace elements of allergens,¹¹ spatial spectral imaging of water content in mushrooms and hydration of food products,¹² small scale hydrothermal alteration (work by Harris¹³ and many other areas well beyond traditional remote sensing, surveillance and target detection). Capable, light weight, low-power hyperspectral sensor systems are now readily available from multiple vendors.¹⁴ Recent developments of high throughput, video rate,^{15,16} plenoptic and/or field-widened tomographic imagers^{17,15} offer a number of new sensor options. One example is a high throughput, slit-less FT

instrument, in which two-dimensional spatial intensity variations are modulated by the intensity variation of a white light interferogram on a row by row basis.¹⁸ Such an approach has the major advantage of increased throughput (the slit does not block any of the aperture function), while requiring only deconvolution of the two intensity distributions via a push broom vector.

Two particular areas—precision agriculture and transportation infrastructure including road, rail and pipelines—are in an extremely rapid initial phase of experimentation and adoption. We also make note of a significant recent interest from other wide ranging areas including medicine¹⁹ and artwork inspection.²⁰ Our current efforts are focused on optimising hyperspectral remote sensing for use with lightweight (less than 50 pounds) unmanned aircraft systems (UAS) and to provide the relevant training necessary for future practitioners to construct and deploy full solutions that include the sensor system, data storage and archiving, and an appropriate data decision framework. Several hundred relevant hotlinks pertaining to hyperspectral imaging of the transportation infrastructure are available and provided elsewhere.^{21,22}

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